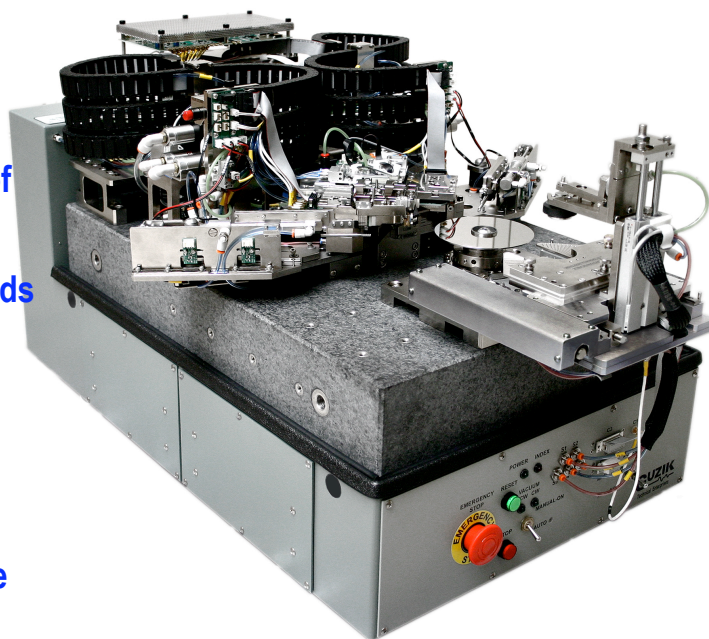


GUZIK PRODUCT BULLETIN

GUZIK DTR 3000 Spinstand with XY-Positioning

For Head, Headstack and Disk Testing

- Embedded Servo with 2–3 kHz bandwidth¹
- Servo Accuracy² 0.4 nm (0.016 μ Inch), 1 σ
- Servo Resolution 0.02 nm (0.001 μ Inch), 1 σ
- Non-Repeatable Run-out (NRRO) in Servo mode² 0.2 – 0.6 nm (0.008 – 0.024 μ Inch), 1 σ
- Positioning repeatability³ of 0.6 – 1.0 nm (0.024 – 0.039 μ Inch) Peak-to-Peak deviation of track profile slope
- Mounting both up-facing and down-facing heads from the top
- Fast track-to-track seek for Media Scanning applications
- Vacuum and screw clamping disk chucks
- Combloader and Head Stack toolings available
- Crashproof XY-Positioning to protect spindle⁴



Guzik DTR 3000 XY-positioning spinstand uses the X and Y coarse positioning stages actuated by linear motors and the micro-positioning stage actuated by the piezo element aligned with X coordinate axis to place the tested head on the specified track. WITE32 software converts the requested track number and skew angle into X and Y coordinates.

Guzik DTR 3000 spinstand is created for testing Head Gimbal Assemblies (HGA), Head Stack Assemblies (HSA), Head Arm Assemblies (HAA), as well as for the DTR and non-DTR media testing.

¹ With Piezo-Actuator Cartridge, patent pending

² With optional Servo Improvement Package

³ Typical parameter value

⁴ US Patent 7,061,235 B2

Micro-positioning in Servo and Non-Servo Modes

Guzik DTR 3000 spinstand can use one of the two following modes for the head positioning:

- **Non-servo mode**, when the actuation is done by the piezo element with feedback from the glass linear scale.
- **Embedded servo mode**, when the actuation is performed by the piezo element, with feedback from the servo bursts written on the same track with the data signal. These bursts are located at the beginning of every sector. Guzik DTR 3000 spinstand supports sector sampling rates up to 50 kHz (20 μ s).

Using the servo mode assures high positioning repeatability. The head suspension and some spinstand parts expand when temperature changes during measurements. The embedded servo eliminates the positioning errors caused by this thermal expansion. The spinstand in the servo mode also suppresses low-frequency vibrations transmitted from the floor.

The track profile repeatability observed on the Guzik DTR 3000 spinstand in servo mode is 0.6 – 1.0 nm (0.024 – 0.039 μ Inch). The typical non-repeatable runout (NRRO), measured as 1 σ of the Position Error Signal (PES) from the embedded servo, is 0.2 – 0.6 nm (0.008 – 0.024 μ Inch). Repeatability and NRRO significantly depend upon the particular head and media used but are consistent for the same head type. The data above was obtained using a 7200 RPM product.

Advanced Linear Scale Interpolator

Guzik DTR 3000 spinstand features an advanced linear scale interpolator developed by Guzik Technical Enterprises. The spinstand with 2 μ m period glass scales and the interpolator has measurement accuracy of ± 0.3 nm (± 0.012 μ Inch).

Key Features

Guzik DTR 3000 spinstand performs software controlled alignment for each tested head. The alignment procedure takes one second and measures the position of the disk center with accuracy 80 μ Inch (2 μ m). The results can be improved by averaging. The procedure increases the accuracy of track and skew angle positioning. As a result, Guzik DTR 3000 spinstand achieves higher accuracy of WROffset, Writer Width, and Reader Width measurements.

There are no head amplifier boards on the cartridges for Head Loading Mechanism HLM-3000. The new cartridge design has only a small board integrated with a head connector. The head amplifier boards are removed from the cartridges and installed on the swinging platforms of HLM-3000 without sacrificing electrical performance.

Guzik DTR 3000 spinstand can be used for head (HGA, HAA) testing and, after mechanical conversion, for headstack (HSA) testing. Guzik Technical Enterprises offers tooling for specific HGA, HAA, and HSA designs.

Crash-Proof Design

Guzik DTR 3000 is a crash-proof spindstand due to the new patented design of the Head Loading Mechanism HLM-3000. The arms of the V-shaped HLM-3000 are rotated 45 degrees in respect to the X and Y coordinate axes of the spindstand. Such geometrical configuration and the mechanical limit on the movement along the Y axis set the working area over the lower quadrant of a media (see Figure 1). This prevents the cartridge from the collision into the spindle/media when the mechanical parameters of the spindstand or the head geometry are specified incorrectly in the software.

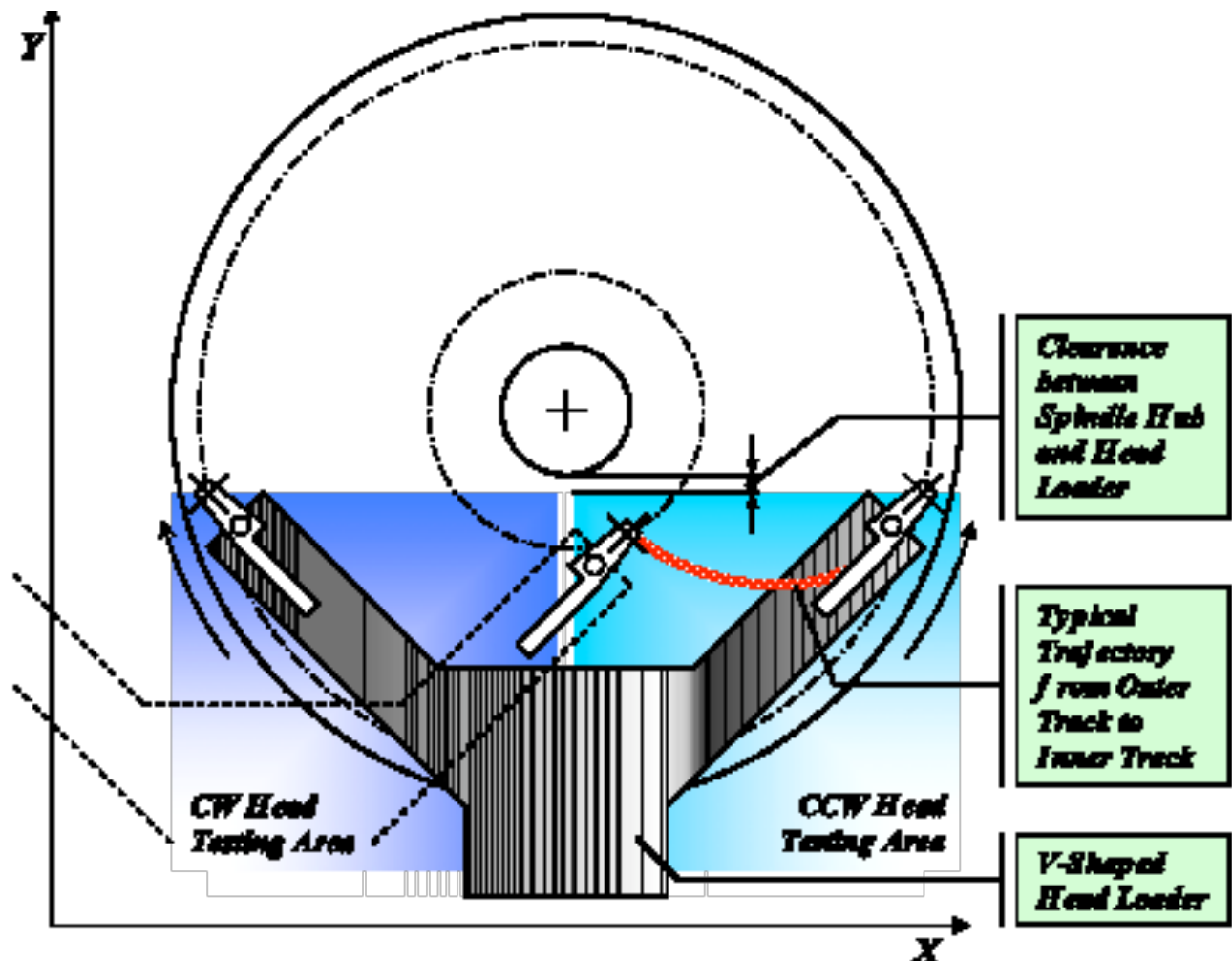


Figure 1: Working Area of HLM-3000

Features and Specifications*:

Air Bearing Spindle

- **Motor:** Brushless DC, programmable 100 RPM – 20,000 RPM
- **Interchangeable Spindle Chucks:**
 - 0.85", 1.0", 1.8", 2.5", and 3.0"/3.5" available
 - Vacuum version and screw clamping version
- **RPM Jitter:** 0.005% typical
- **Acceleration:** 0 – 10,000 RPM in approximately 2.4 seconds with 3.5" disk mounted
- **Balancing:** Included as standard
- **Shroud:** Included as standard (two options: automated for media testing or for HGA testing)

Coarse Positioning Mechanism

- **Actuator Type:** X and Y linear motors
- **Movement Type:** Simultaneous dependent XY trajectory movement
- **Skew Angle Control:** Software controlled skew angles

Micro-Positioning Mechanism

- **Actuator Type:** Piezo element
- **Micro-Positioning Encoder Type:** Heidenhain glass scale encoder and embedded servo
- **Drive Servo:** supports Drive Servo for DTR testing
- **Guzik Servo:** supports Guzik Servo Revision 3 and Revision 4.
- **Local Micro-Positioning Accuracy of Glass Scale within Piezo Range:** $\pm 0.3\text{nm}$ ($\pm 0.012\text{ }\mu\text{Inch}$)
- **Position Repeatability:** 0.6 – 1.0 nm / 0.024 – 0.039 μInch typical, measured as maximum deviation of the track profile slope in servo mode (measured at 7200 RPM)
- **Non-Repeatable Runout:** 0.2 – 0.6 nm / 0.008 – 0.024 μInch typical, 1 σ (measured at 7200 RPM with Piezo-Actuator Cartridge)
- **Hysteresis:** Closed loop system, no hysteresis

Head Loading Mechanism

- HGA, HAA, and HSA tooling
- Tooling can be designed to custom specifications

Spinstand Electronics

- **Separate Control Box and Spinstand Frame** for electrical and mechanical noise reduction
- **Control Box Type:** SCB DTR 3000 control box
- **Connection to PC:** USB interface

Physical

Spinstand

Size: 32" x 19" x 17"

Weight: 256 lbs

Control Box

Size: 18" x 18" x 8"

Weight: 36 lbs

Operational

- **Environmental:** 15° C to 40° C, 90% maximum relative humidity, with no condensation, clean room environment
- **Power Supply:**
 - 110 VAC \pm 15% 50/60 Hz, 3 A approximately
 - 230 VAC \pm 15% 50/60 Hz, 2 A approximately
- **Air Supply:**
 - 90 PSI minimum, clean dry air
- **Air Consumption:**
 - 1.6 scfm mass airflow, typical with vacuum chuck

** Specifications are subject to change without notice*

Performance Measurements

The Track Profile Plot on Figure 2 demonstrates typical 0.6 – 1.0 nm / 0.024 – 0.039 μ Inch positioning repeatability of the Guzik DTR 3000 spindast. Signal was written on the track and the amplitude of the read signal was measured at 5 nm / 0.2 μ Inch increments across the track. The measurements were repeated 50 times in forward direction, and 50 times in backward direction.

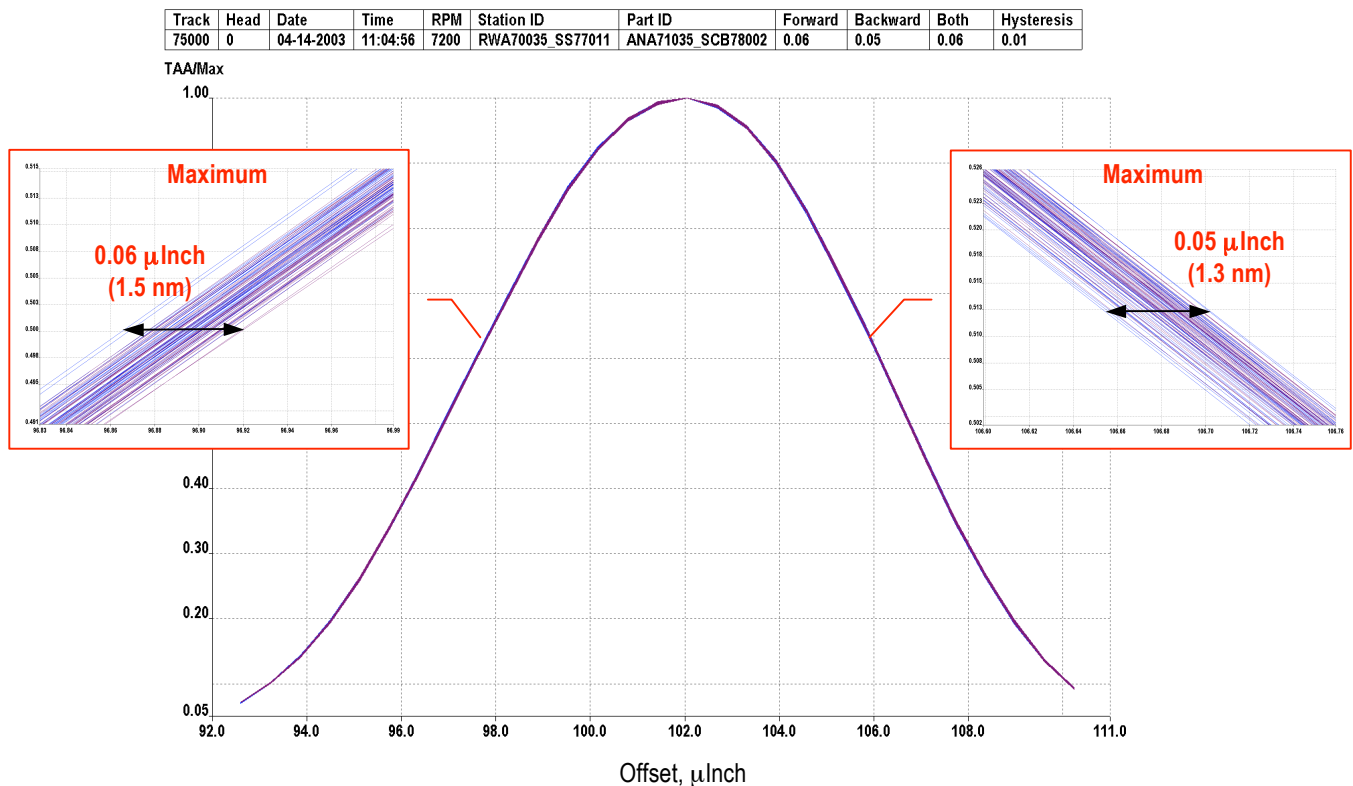


Figure 2: Normalized Track Profile Plot (50 Runs Forward + 50 Runs Backward)

The figures below demonstrate Position Error Signal (PES) measured on DTR 3000 spind. Position error signal is derived from servo bursts written on the media in every sector. Each sector delivers one position error value, expressed in nano-meters. PES was captured for 800 consecutive revolutions and plotted in time on Figure 3 and Figure 4.

The standard deviation (one sigma) of PES data in every sector characterizes the non-repeatable runout (NRRO) of the head. The NRRO value shown on the plots below is 0.2 – 0.6 nm (0.008 – 0.024 μ Inch), measured at 7200 RPM with Piezo-Actuator Cartridge.

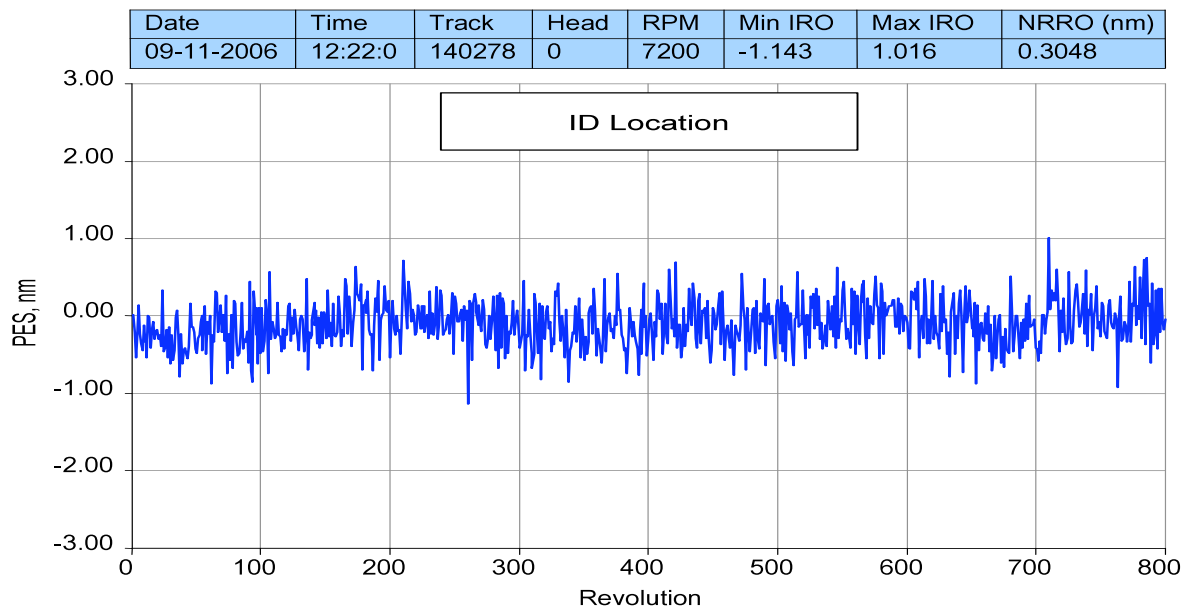


Figure 3: Position Error Signal at ID

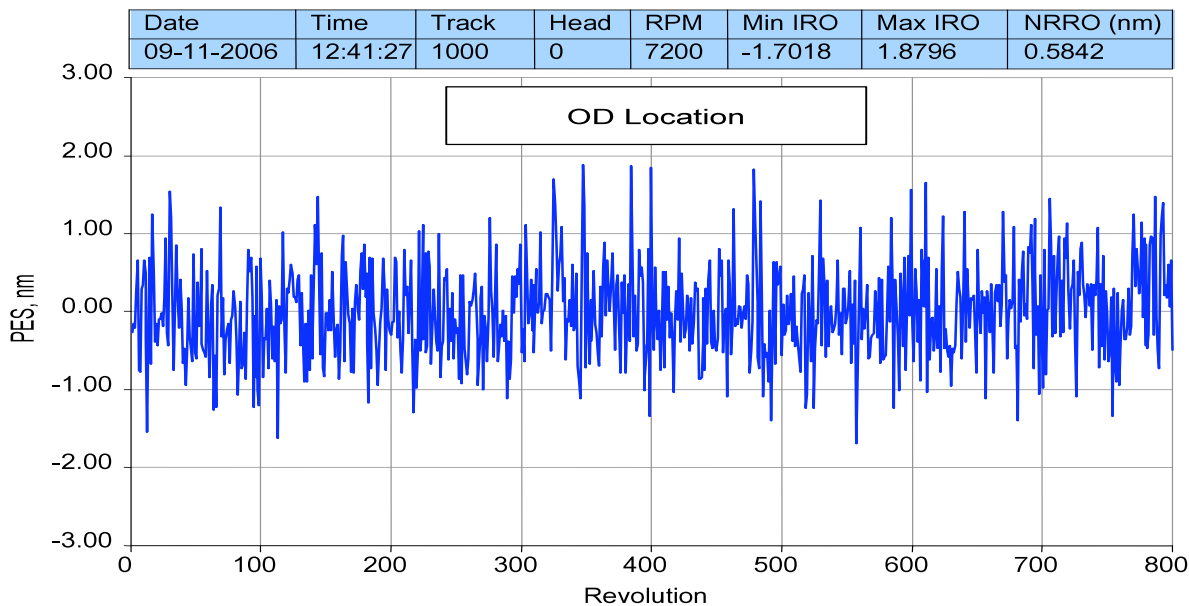


Figure 4: Position Error Signal at OD